

# Product datasheet

Specifications



## variable speed drive, Altivar Machine ATV320, 11kW, 380 to 500V, 3 phases, compact

ATV320D11N4C

### Main

Range of product	Altivar Machine ATV320
Product or component type	Variable speed drive
Product specific application	Complex machines
Variant	Standard version
Format of the drive	Compact
Mounting mode	Wall mount
Communication port protocol	Modbus serial CANopen
Option card	Communication module, CANopen Communication module, EtherCAT Communication module, Profibus DP V1 Communication module, PROFINET Communication module, Ethernet Powerlink Communication module, EtherNet/IP Communication module, DeviceNet
[Us] rated supply voltage	380...500 V - 15...10 %
nominal output current	27.7 A
Motor power kW	11 kW for heavy duty
EMC filter	Integrated
IP degree of protection	IP20

### Complementary

Discrete input number	7
Discrete input type	STO safe torque off, 24 V DC, impedance: 1.5 kOhm DI1...DI6 logic inputs, 24 V DC (30 V) DI5 programmable as pulse input: 0...30 kHz, 24 V DC (30 V)
Discrete input logic	Positive logic (source) Negative logic (sink)
Discrete output number	3
Discrete output type	Open collector DQ+ 0...1 kHz 30 V DC 100 mA Open collector DQ- 0...1 kHz 30 V DC 100 mA
Analogue input number	3
Analogue input type	AI1 voltage: 0...10 V DC, impedance: 30 kOhm, resolution 10 bits AI2 bipolar differential voltage: +/- 10 V DC, impedance: 30 kOhm, resolution 10 bits AI3 current: 0...20 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration), impedance: 250 Ohm, resolution 10 bits
Analogue output number	1

<b>Analogue output type</b>	Software-configurable current AQ1: 0...20 mA impedance 800 Ohm, resolution 10 bits Software-configurable voltage AQ1: 0...10 V DC impedance 470 Ohm, resolution 10 bits
<b>Relay output type</b>	Configurable relay logic R1A 1 NO electrical durability 100000 cycles Configurable relay logic R1B 1 NC electrical durability 100000 cycles Configurable relay logic R1C Configurable relay logic R2A 1 NO electrical durability 100000 cycles Configurable relay logic R2C
<b>Maximum switching current</b>	Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V DC
<b>Minimum switching current</b>	Relay output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC
<b>Method of access</b>	Slave CANopen
<b>4 quadrant operation possible</b>	True
<b>Asynchronous motor control profile</b>	Voltage/frequency ratio, 5 points Flux vector control without sensor, standard Voltage/frequency ratio - Energy Saving, quadratic U/f Flux vector control without sensor - Energy Saving Voltage/frequency ratio, 2 points
<b>Synchronous motor control profile</b>	Vector control without sensor
<b>Maximum output frequency</b>	0.599 kHz
<b>Acceleration and deceleration ramps</b>	Linear U S CUS Ramp switching Acceleration/deceleration ramp adaptation Acceleration/deceleration automatic stop with DC injection
<b>Motor slip compensation</b>	Automatic whatever the load Adjustable 0...300 % Not available in voltage/frequency ratio (2 or 5 points)
<b>Switching frequency</b>	2...16 kHz adjustable 4...16 kHz with derating factor
<b>Nominal switching frequency</b>	4 kHz
<b>Braking to standstill</b>	By DC injection
<b>Brake chopper integrated</b>	True
<b>Line current</b>	36.6 A at 380 V (heavy duty) 25.6 A at 500 V (heavy duty)
<b>Maximum input current</b>	36.6 A
<b>Maximum output voltage</b>	500 V
<b>Apparent power</b>	22.2 kVA at 500 V (heavy duty)
<b>Network frequency</b>	50...60 Hz
<b>Relative symmetric network frequency tolerance</b>	5 %
<b>Prospective line Isc</b>	22 kA
<b>Base load current at high overload</b>	27.7 A
<b>Power dissipation in W</b>	Fan: 370 W at 380 V, switching frequency 4 kHz
<b>With safety function Safely Limited Speed (SLS)</b>	True
<b>With safety function Safe brake management (SBC/SBT)</b>	False

With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	True
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque off (STO)	True
With safety function Safely Limited Position (SLP)	False
With safety function Safe Direction (SDI)	False
Protection type	Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive
Width	180 mm
Height	330 mm
Depth	198.0 mm
Product weight	6.8 kg
Transient overtorque	170...200 % of nominal motor torque

## Environment

Operating position	Vertical +/- 10 degree
Product certifications	CE ATEX NOM GOST EAC RCM KC
Marking	CE ATEX UL CSA EAC RCM
Standards	IEC 61800-5-1
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s <sup>2</sup> at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s <sup>2</sup> at 13...200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 2...13 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3

Volume of cooling air	156.0 m3/h
Overvoltage category	III
Regulation loop	Adjustable PID regulator
Speed accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn
Pollution degree	2
Ambient air transport temperature	-25...70 °C
Ambient air temperature for operation	-10...50 °C without derating 50...60 °C with derating factor
Ambient air temperature for storage	-25...70 °C

## Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	22.500 cm
Package 1 Width	25.500 cm
Package 1 Length	42.000 cm
Package 1 Weight	7.753 kg
Unit Type of Package 2	P06
Number of Units in Package 2	6
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	57.253 kg



## Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing “Use Better, Use Longer, Use Again” campaign to extend product lifetimes and recyclability.

[Environmental Data explained >](#)

[How we assess product sustainability >](#)

### Environmental footprint

Carbon footprint (kg.eq.CO2 per CR, Total Life cycle) **11030**

Environmental Disclosure [Product Environmental Profile](#)

## Use Better

### Materials and Substances

Packaging made with recycled cardboard **Yes**

Packaging without single use plastic **No**

[EU RoHS Directive](#) **Pro-active compliance (Product out of EU RoHS legal scope)**

SCIP Number **113ee97a-ee48-474b-8a47-e855ec6d6d22**

REACH Regulation [REACH Declaration](#)

### Energy efficiency

Product contributes to saved and avoided emissions **Yes**

## Use Again

### Repack and remanufacture

Circularity Profile [End of Life Information](#)

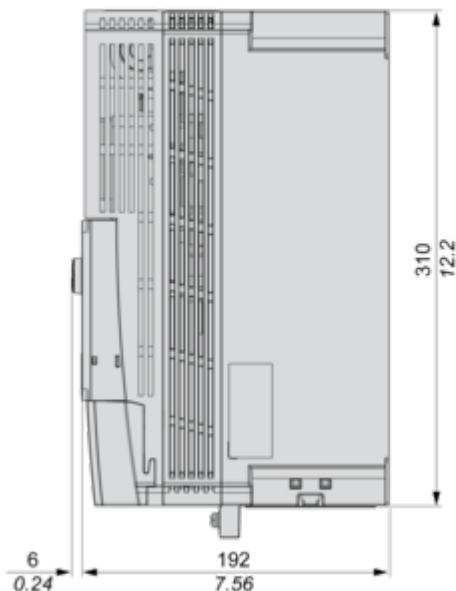
Take-back **No**

WEEE **The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins**

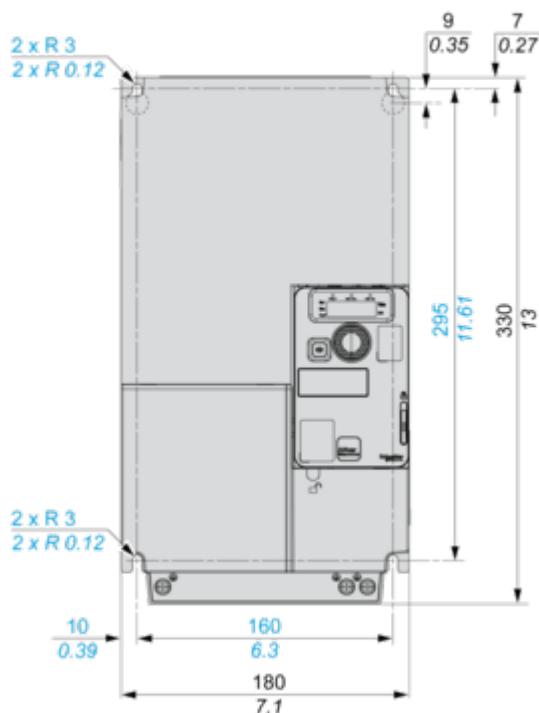
## Dimensions Drawings

## Right and Front Views without EMC Plate

mm  
in.

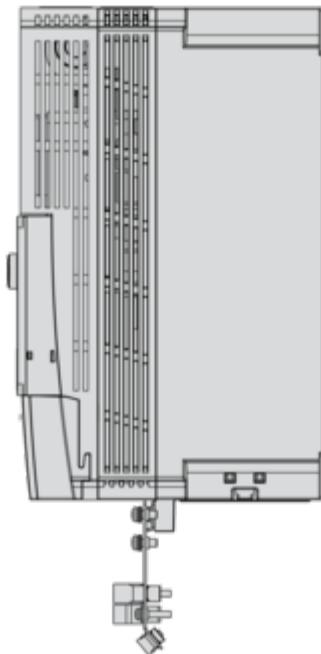


mm  
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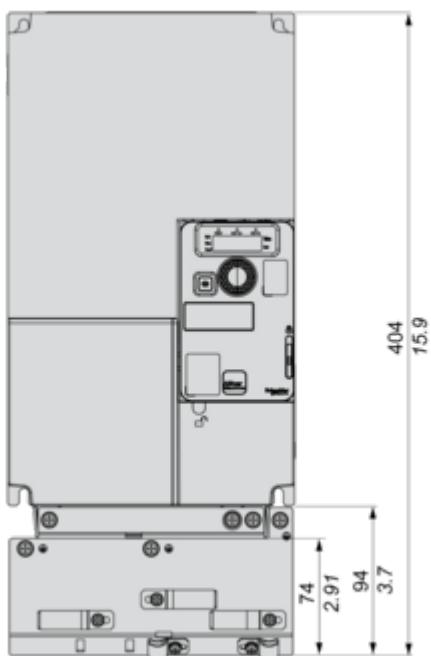


## Right and Front Views with EMC Plate

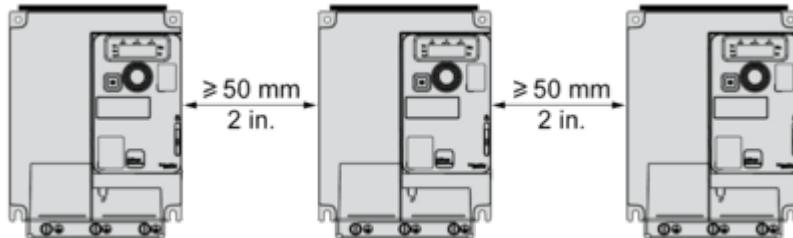
mm  
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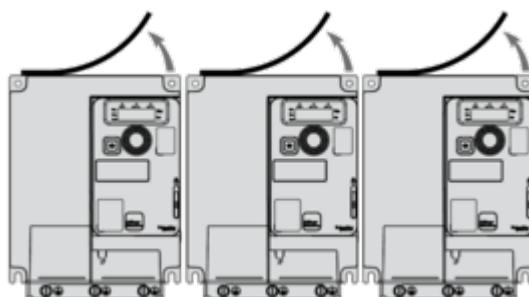
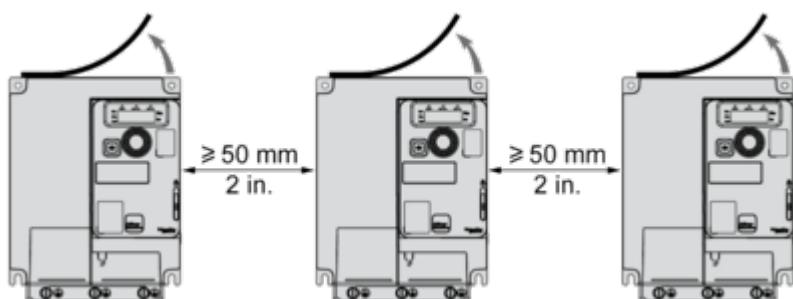
mm  
in.



## Mounting and Clearance

**Mounting Types****Mounting Type A: Individual with Ventilation Cover**

Only Possible at Ambient Temperature Less or Equal to 50 °C (122 °F)

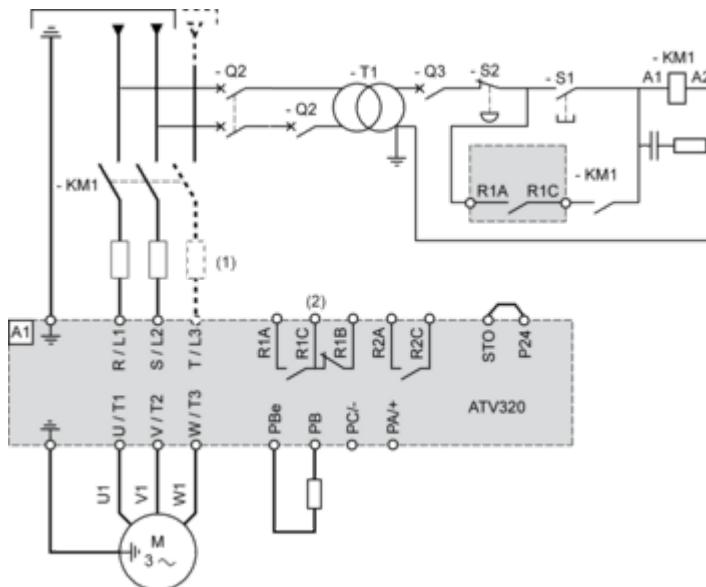
**Mounting Type B: Side by Side, Ventilation Cover Removed****Mounting Type C: Individual, Ventilation Cover Removed**

For Operation at Ambient Temperature Above 50 °C (122 °F)

## Connections and Schema

## Connection Diagrams

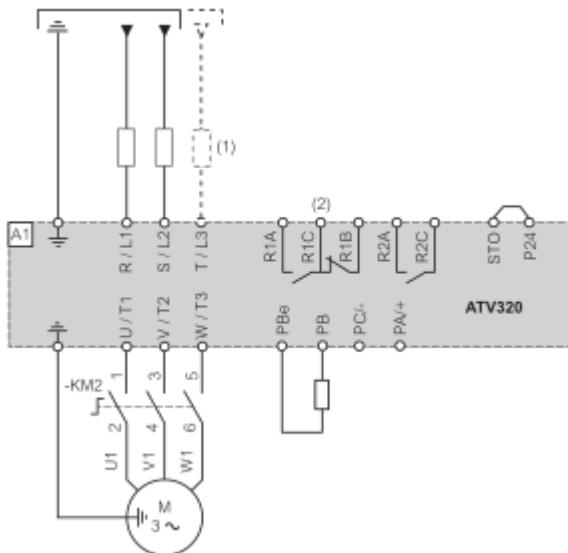
## Single or Three-phase Power Supply - Diagram With Line Contactor



(1) Line choke (if used)

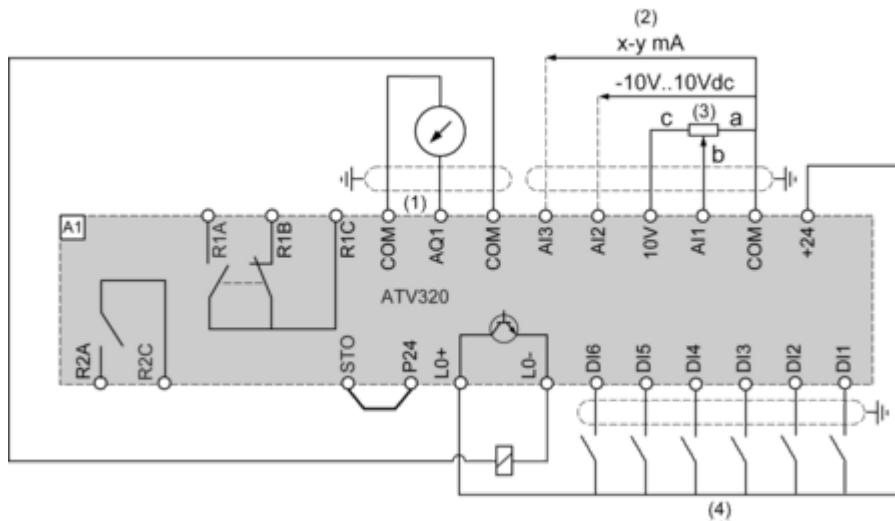
(2) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.

## Single or Three-phase Power Supply - Diagram With Downstream Contactor



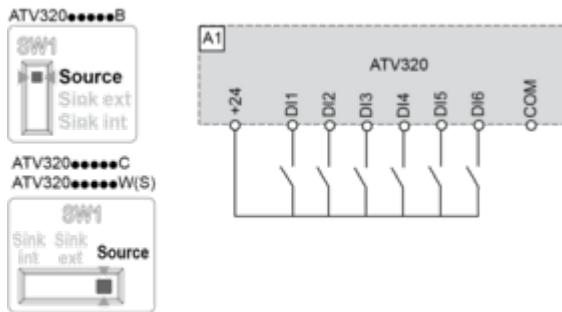
(1) Line choke (if used)

(2) Use relay output R1 set to operating state Fault to switch Off the product once an error is detected.

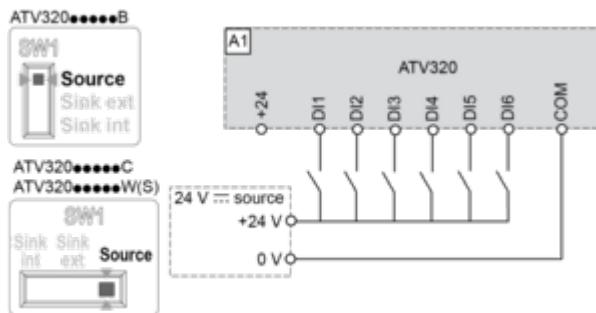
**Control Block Wiring Diagram**

## Digital Inputs Wiring

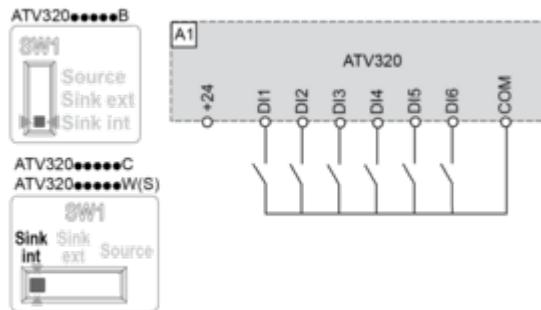
### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



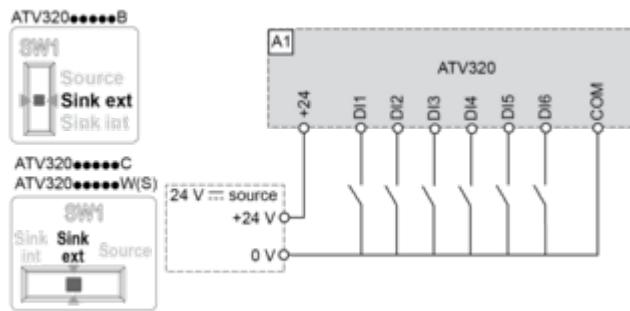
### Switch Set to SRC (Source) Position and Use of an External Power Supply for the Digital Inputs



### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs



### Switch Set to EXT Position Using an External Power Supply for the Digital Inputs

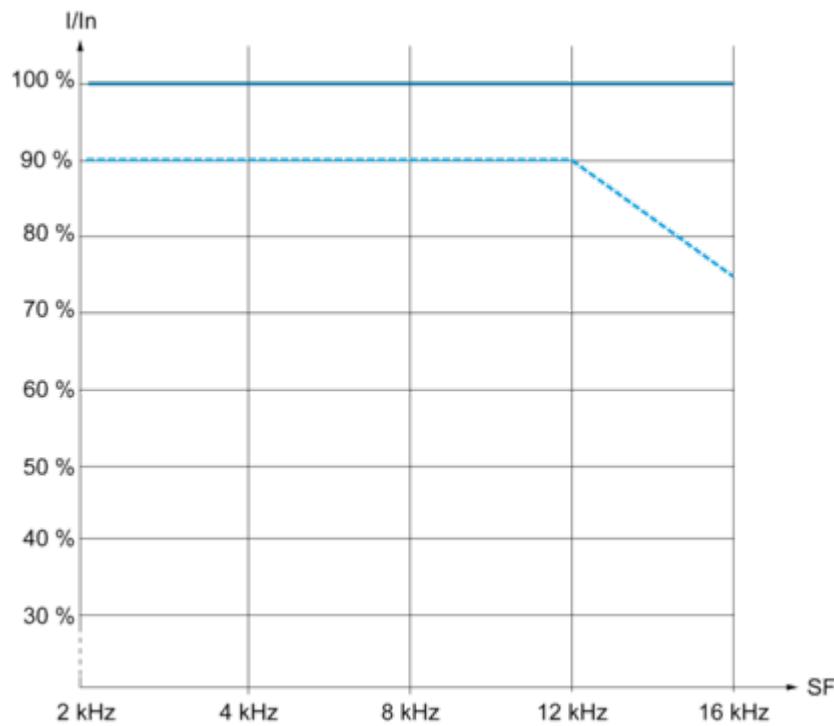


#### NOTE :

- STO input is also connected by default on a 24 Vdc terminal. If the external power supply is switched off, the function STO will be triggered.
- To avoid triggering the STO function when switching-on the product, the external power supply must be previously switched on.



## Performance Curves

Derating Curves

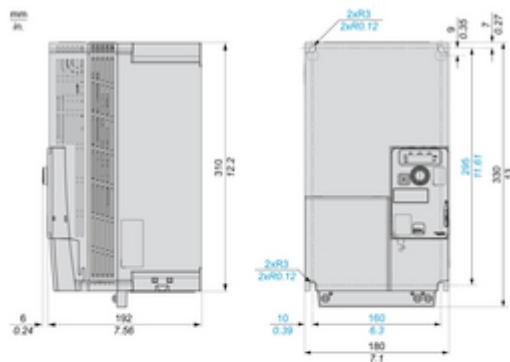
— 40 °C (104 °F) - Mounting type A and B  
- - - 50 °C (122 °F) - Mounting type A and B

**In** : Nominal Drive Current

**SF** : Switching Frequency

## Technical Illustration

## Dimensions



With EMC Plate

